

LINES TRACKERS ROBOT SENSOR INFRARED LINES THROUGH AT89C52 MICROCONTROLLER

Ari Wibowo susanto, 20401044, Drs. Lingga Hermanto, MMSI.

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STMIK Jakarta STI&K

<http://www.jak-stik.ac.id>

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Abstract:

Autonomous Mobile Robot (AMR) is the robot that has the ability to move towards a certain point without human intervention. This research has built an AMR which has a mission to follow a line that has been determined by using infrared light as the sensor line. The purpose of this thesis is to design and implement a Line Tracer Robot using AT89C52 microcontroller and infrared sensors. AT89C52 microcontroller is used as the control center. Interruption of its facilities is very useful in responding to a line that is detected by sensors in real-time line.

Bibliography: 10 (1988 - 2002)

